

WROCŁAW UNIVERSITY OF ENVIRONMENTAL AND LIFE SCIENCES

OPTIMUM STOCHASTIC MODELING FOR GNSS TROPOSPHERE DELAY ESTIMATION IN REAL-TIME

<u>Tomasz Hadaś</u>¹, Felix Norman Teferle², Kamil Kaźmierski¹, Paweł Hordyniec¹, Jarosław Bosy¹

1) Institute of Geodesy and Geoinformatics, Wroclaw University of Environmental and Life Sciences

2) Geophysics Laboratory, University of Luxembourg

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Presentation plan



- 2. Methodology
- 3. Results:
 - RWPN global grids
 - Case studies
 - Overall results
- 4. Conclusion

Motivation

- 1. IGS-RTS -> Real-time GNSS meteorology
- 2. Investigations on:
 - elevation dependent weighting (Ning 2012),
 - multi-GNSS solution (Li et al. 2015),
 - relation between clock and ZTD accuracy (Shi et al. 2015),
 - observation model, AR, I2+ effects (Ahmed et al. 2016).
- 3. Stochastic modeling random walk (RW) with process noise (PN):
 - RWPN=**5mm/√h** for ZWD in PPP (Kouba and Horoux 2001),
 - RWPN=**20mm/√h** for ZWD constraint (Pacione et al. 2009),
 - constraining based on **initial empirical test** (Dousa et al. 2013),
 - RWPN of **about 5-10 mm/√h** (Lu et al. 2015).
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- 7. Pacione R, Vespe F (2008) Comparative studies for the assessment of the quality of near-real-time GPS-derived atmospheric parameters. J Atmos Ocean Tech 25:701–714
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Random walk theory

ZWD random walk - Markov (memory-less) process:

$$\boldsymbol{E}(|\boldsymbol{S}_n(\boldsymbol{\varepsilon})|) = \boldsymbol{\varepsilon}\sqrt{n}$$

S - translation distance, n – number of steps, ε – step length

Adopting for troposhere :

$$E(|\Delta T_{t+\delta t} - \Delta T_t|) = \varepsilon \sqrt{\delta t}$$

 ΔT – tropo delay, δt – time interval, ε = RWPN

To estimate RWPN if a time series of ΔT is known:

$$E(\varepsilon) = |\Delta T_{t+\delta t} - \Delta T_t| / \sqrt{\delta t}$$

YSSK

ALIC

BAKO

•NRIL

ABPO

CAS1

LCK?

REYK HERT• • WROC DRAO **BRMU**• **BSHM MKEA** • BOGT NKLG BRAZ **ISPA** • PARC 4000 BRAZ BRMU BSHM BSHM BSHM CAS1 CAS1 CAS1 LCK3 NKEA NKEA NKEA NKEA ന

Data and test campaigns

GNSS data

- 20 IGS stations (RINEX)
- **RTS IGS03 stream**
- reference: IGS Final ZTD $(5 \text{ min}, \sigma = 1-2 \text{ mm})$

Test campaigns:

- DoY 155-161,2013
- DoY 330-336, 2015

NWP models:

- ECMWF (from VMF1) (2.0 x 2.5 deg grid, 6 hours)
- GFS4 forecast (ray-tracing) (0.5 x 0.5 deg grid, 3 hours)



Station name

Processing variants

Simulated real-time mode in GNSS-WARP software:

- 1. **Fixed** initial empirical testing
 - RWPN: from 1 mm/ \sqrt{h} to 10 mm/ \sqrt{h} (with 1 mm/ \sqrt{h} step)
- 2. NWP based **yearly** mean RWPN
 - use ZWD time-series from the past year
- 3. NWP based **seasonal** mean RWPN
 - use 30-day window of corresponding season, last year
- 4. NWP forecast based **dynamic** RWPN
 - use NWM forecast to estimate RWPN in real-time

Objective: Provide optimum RWPN setting without initial empirical tests.

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Yearly mean RWPN grids



- Hydrostatic and wet RWPN are geographically dependent
- RWPN repeats year by year
- Wet RWPN: 0.1 12.0 mm/ \sqrt{h} , mean 5.0mm/ \sqrt{h} , Europe ~ 5mm \sqrt{h}

Seasonal mean RWPN grids



- Hydrostatic and wet RWPN vary over seasons
- Wet RWPN varies slightly over lands, significantly over oceans
- Wet RWPN: $0.1 16.5 \text{ mm}/\sqrt{h}$, mean $4.8 \text{mm}/\sqrt{h}$, Europe $\sim 5 \text{mm}/\sqrt{h}$

Case study – station HERT



- good agreement of RT solutions with the the Final solution
- small differences among RT solutions
- the larger the RWPN, the smaller % of epochs, best fixed =3 in 2013, =7 in 2015
- yearly and seasonal approach are almost as good as the best fixed (StdDev & %)
- dynamic approach reduced StdDev (18%!), % of epochs is high

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Case study – station PARC



- best fixed RWPN: 5mm/√h in 2013 and 2015
- yearly and seasonal equally good
- dynamic variant more accurate, less available

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Case study – station YSSK



- best fixed RWPN: 10mm/ \sqrt{h} in 2013 and 2015, but significant loss of availability!
- optimum RWPN: 5mm/√h
- yearly and seasonal unambiguous among years
- dynamic variant more accurate, less available

Comparison of wet RWPN among variants



No single globally optimum value of RWPN!

Optimum RWPN is time and location dependent

Solution availability

2013:

- >95% epochs for 17/20 stations
- worse stations BOGT, LCK4, MKEA

2015:

- >95% epochs for 19/20 stations
- worse stations MKEA

Yearly apporach similar to Fix 6 Seasonal appraoch < Yearly apporach

Dynamic appraoch:

- 76% epochs for MKEA!
- slighlty less epochs for other stations



Solution accuracy

2013:

- For Fix 5-10, yearly and seasonal:
 - error: average=10mm, max<20

2015:

- Fix 6 is the best empirical value:
 - mean:9.7mm
 - range:3.8mm 16.8mm
- Yearly slightly better than Fix 6
- Seasonal slightly worse than Yearly
- Dynamic better than Fix 6:
 - mean:9.2
 - range:4.2mm 14.7mm



Overall evaluation

2013

	RW	'PN		Epoch	S	StdDev		
	[mm	/√h]		[%]		[mm]		
	Min	Max	Avg	Min	Max	Avg	Min	Max
Indiv. Fixed	1.0	10.0	93.8	43.3	98.5	10.3	6.3	17.4
Yearly	2.2	8.6	93.5	50.0	98.6	11.1	6.6	18.0

		RWPN			Epoch	S	StdDev		
		[mm/√h]		[%]			[mm]		
ດ		Min	Max	Avg	Min	Max	Avg	Min	Max
5	Indiv. Fixed	1.0	10.0	97.7	89.9	99.6	8.9	3.6	14.2
N	Yearly	2.2	9.3	95.4	37.5	99.6	9.7	3.7	17.7
-11	Dynamic	0.0	45.3	96.1	76.3	99.6	9.2	4.2	14.7

Conclusions and recommendations

- 1. Optimum RWPN is **location and time dependent** parameter.
- 2. There is no single globally optimum value of RWPN.
- 3. The best results are obtained where RWPN is determined empirically, but:
 - it is very time consuming (# station, time series length),
 - / it may still varies depending on the test-period.
- 4. Instead of using empirical apporach, one can:
 - use global yearly RWPN grid (static, look-up table)
 - perform NWP ray-tracing using short-term forecast data to apply dynamic RWPN

Optimum stochastic modeling for GNSS troposphere delay estimation in real-time



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THANK YOU!



Tomasz Hadaś Kamil Kaźmierski Paweł Hordyniec Jarosław Bosy



Norman Teferle

Presenting & corresponding author: Tomasz Hadaś Institute of Geodesy and Geoinformatics Wroclaw University of Environmental and Life Sciences

www.up.wroc.pl