

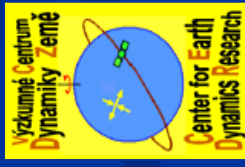
8th Czech-Polish workshop on Recent Geodynamics of the Sudeten
and Adjacent Areas
Boguszyn, 29.-31. March 2007

Data processing of the GNSS observations of the GEONAS network - the NAVSTAR and GLONASS satellite systems and the effects of extreme meteorological conditions

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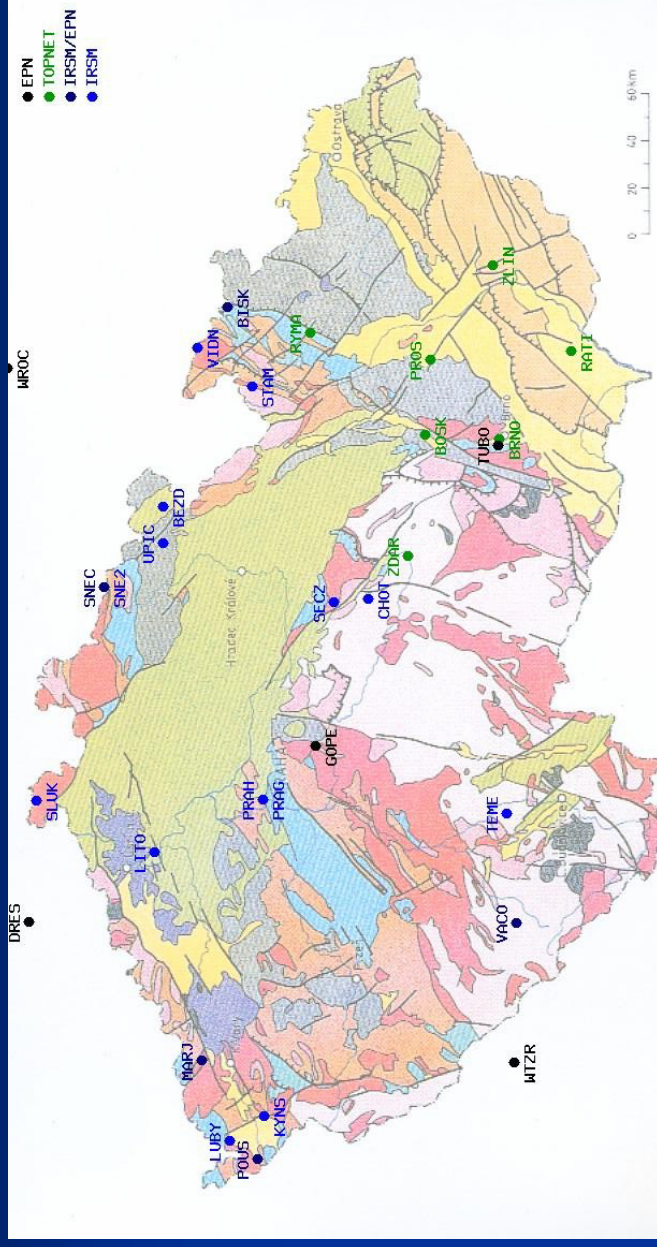
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Outline

1. Processing of NAVSTAR and GLONASS observations
 - processed data and characteristics of the processing
 - comparison results
2. Effects of extreme meteorological conditions
 - mountain observatories - their monitoring and processing

The processed data



Schematic map of the
processed observatories

- 17 permanent observatories of the GEONAS network
- 6 observatories of the network TopNET
- 6 observatories of the network EUREF– GOPE, TUBO, BOR1, POTS, WTZR and PENC
- processed data: 1.-30. September 2006

Characteristics and proceeding of data processing

Input data:

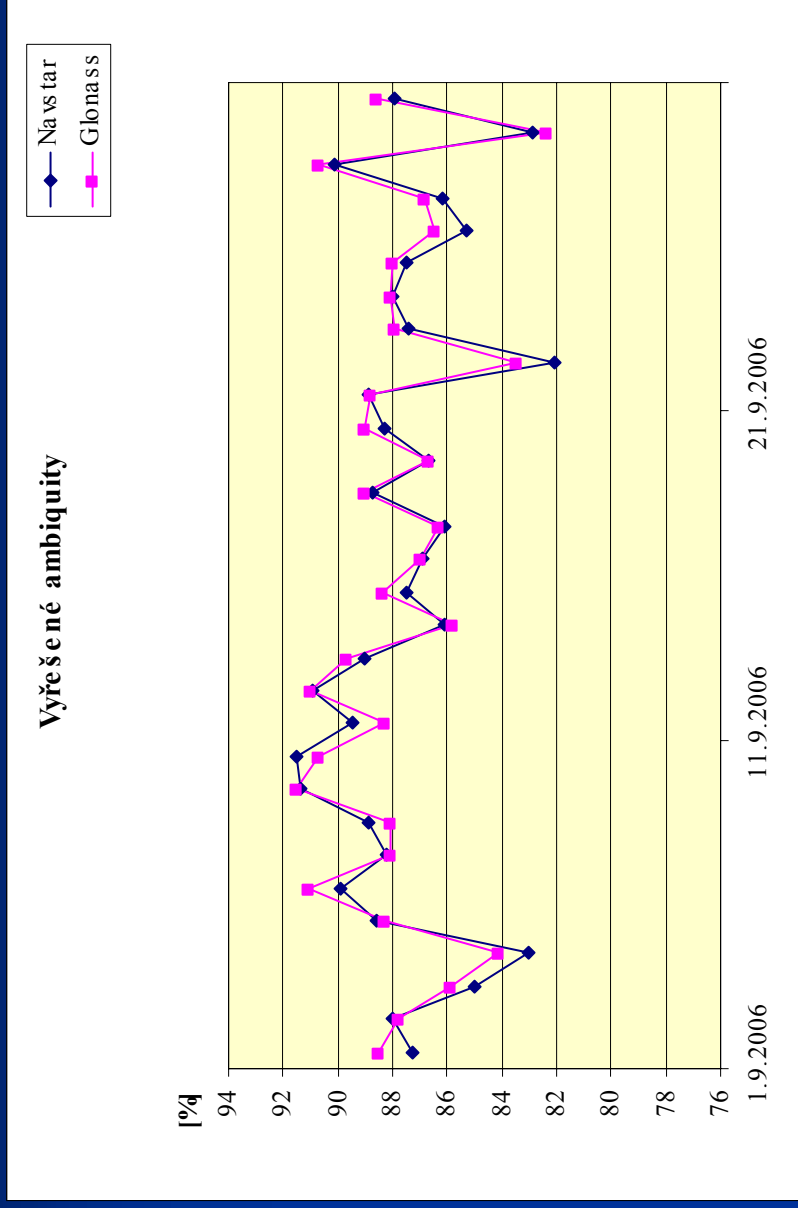
- registered RINEX data with the interval of 30 sec and 5° elevation mask
- CODE precise orbits, ERP, time corrections (NAVSTAR and GLONASS)

Processing procedure:

BERNESE GPS software version 5.0

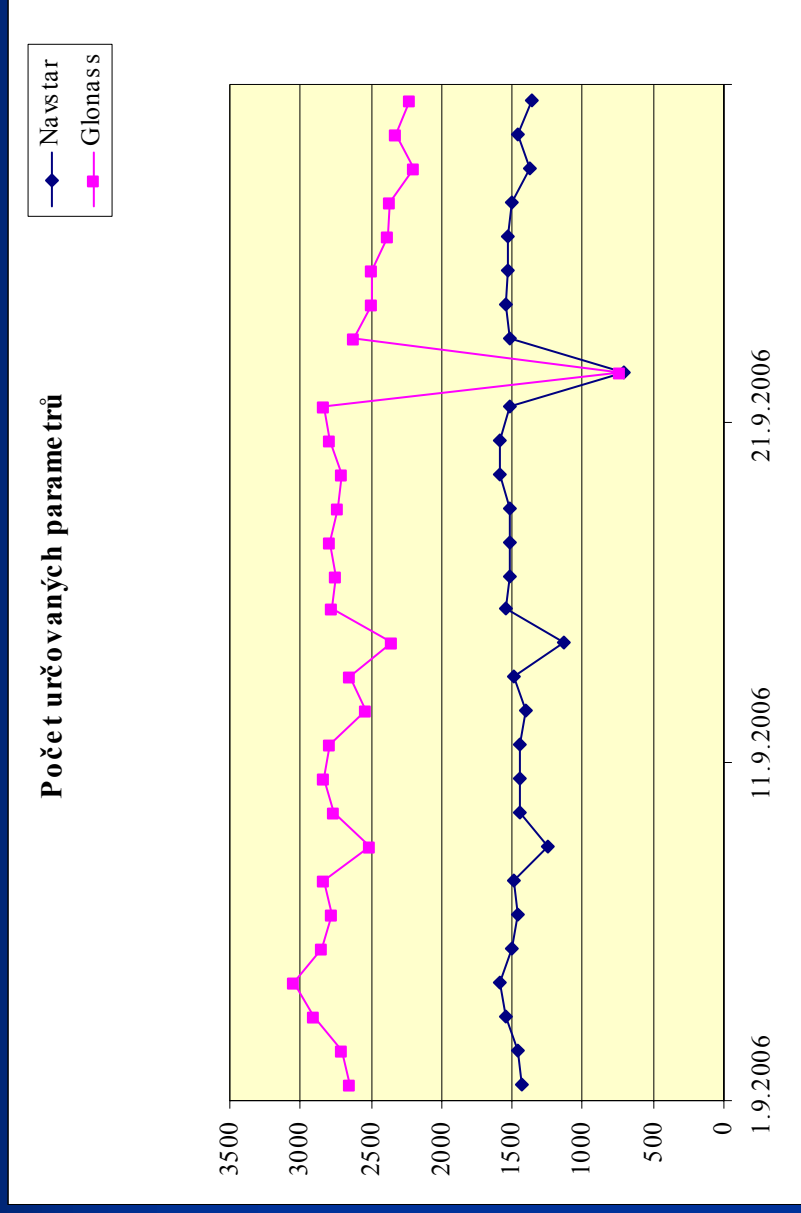
- processing method – double difference
- processing in two passes
 1. NAVSTAR only
 2. NAVSTAR + GLONASS
- processing outcome comparison

Ambiguity fixing



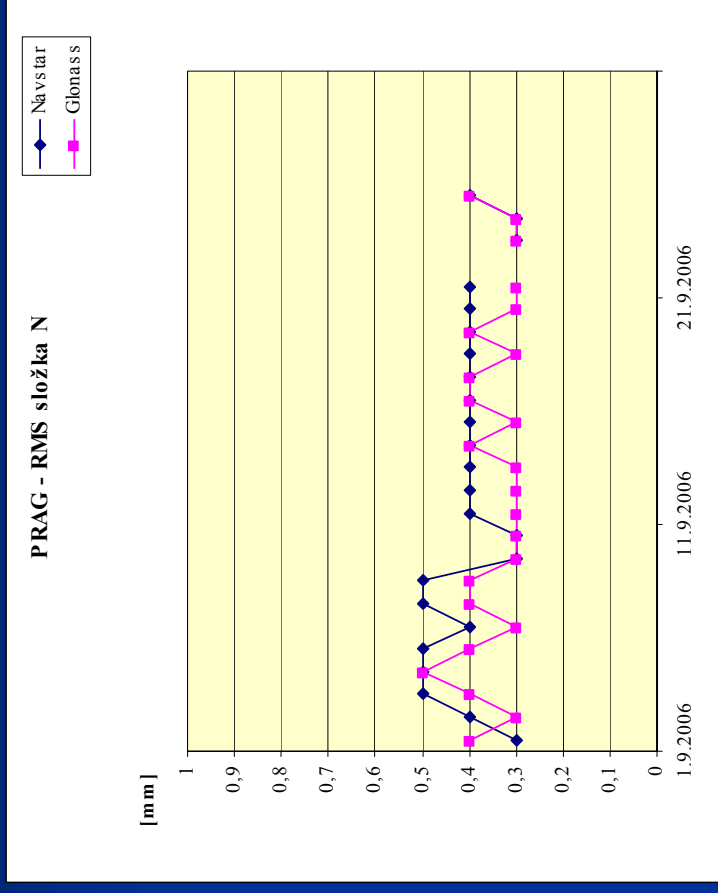
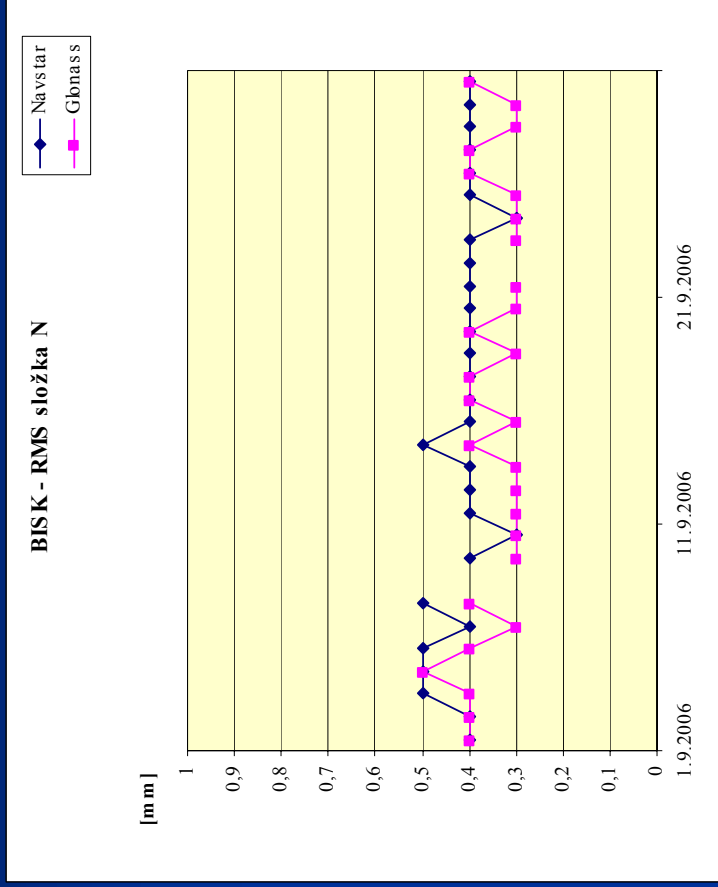
- the percentage of resolved ambiguities is higher in combined solution

Number of parameters



- the number of parameters double for NAVSTAR + GLONASS solutions

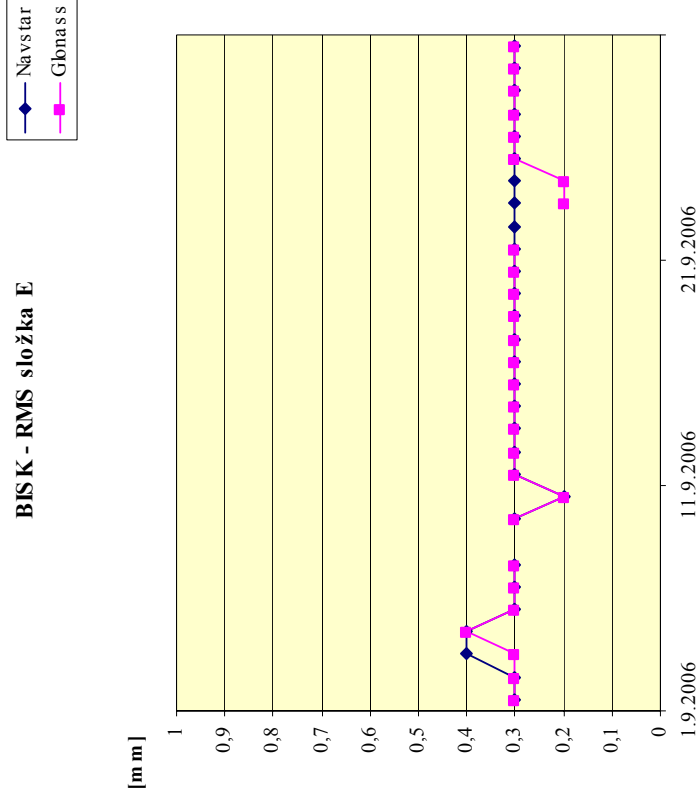
Solution accuracy – N component



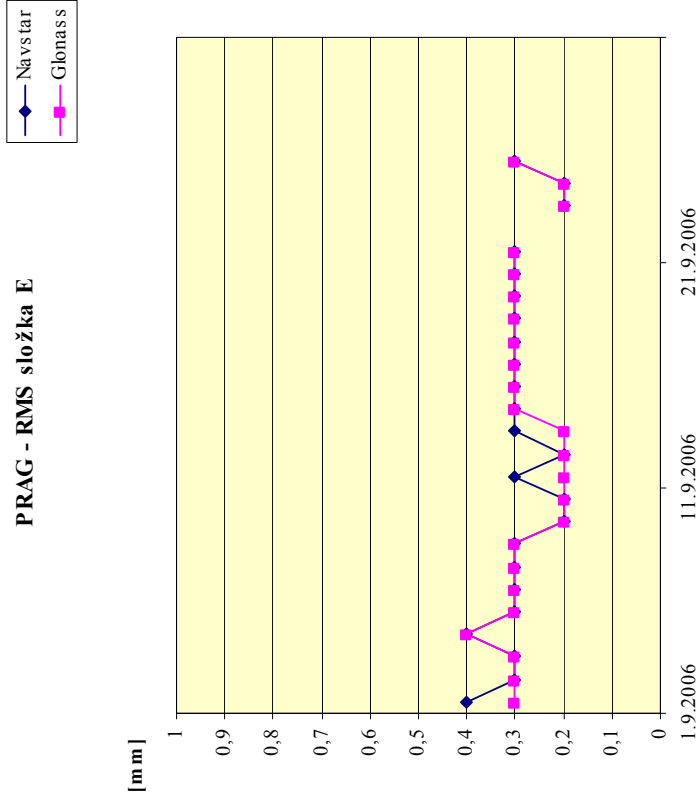
- the combined solution shows lower RMS for most days

Solution accuracy – E component

BISK - RMS složka E

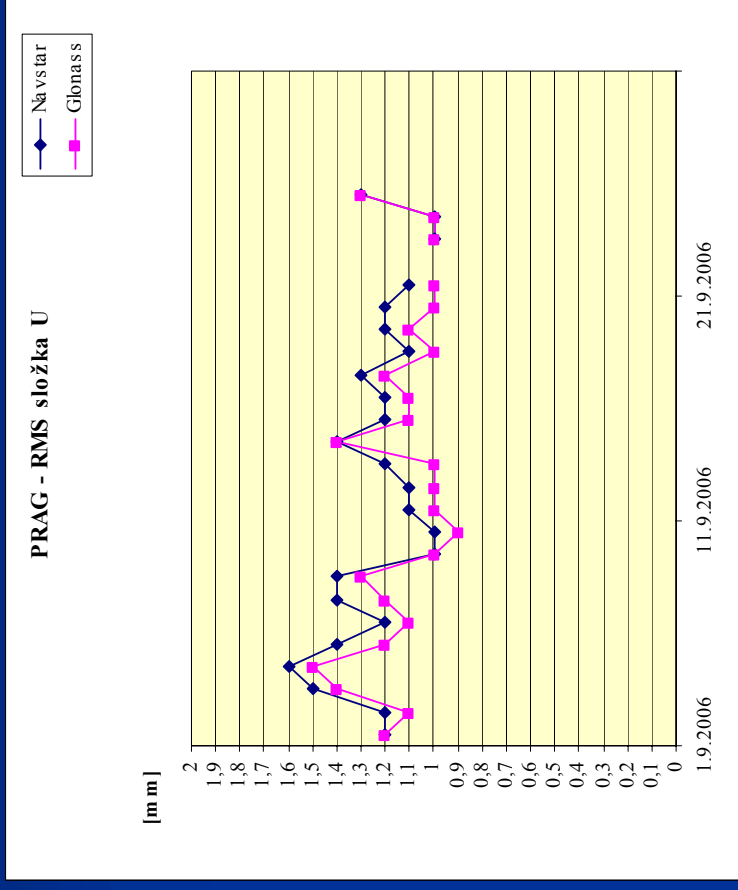
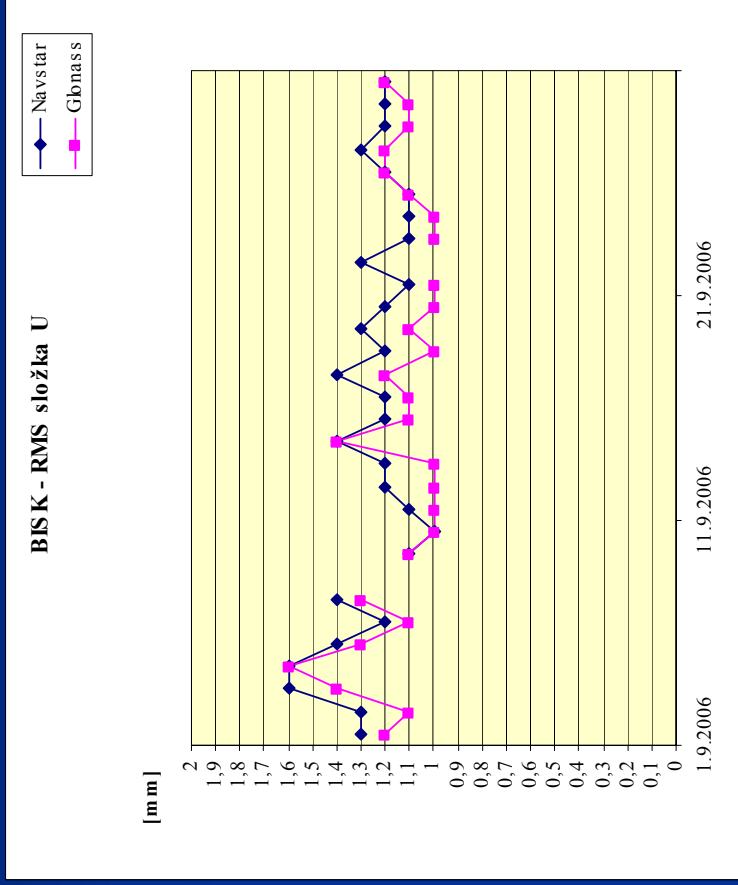


PRAG - RMS složka E



- the combined solution shows lower or equal RMS

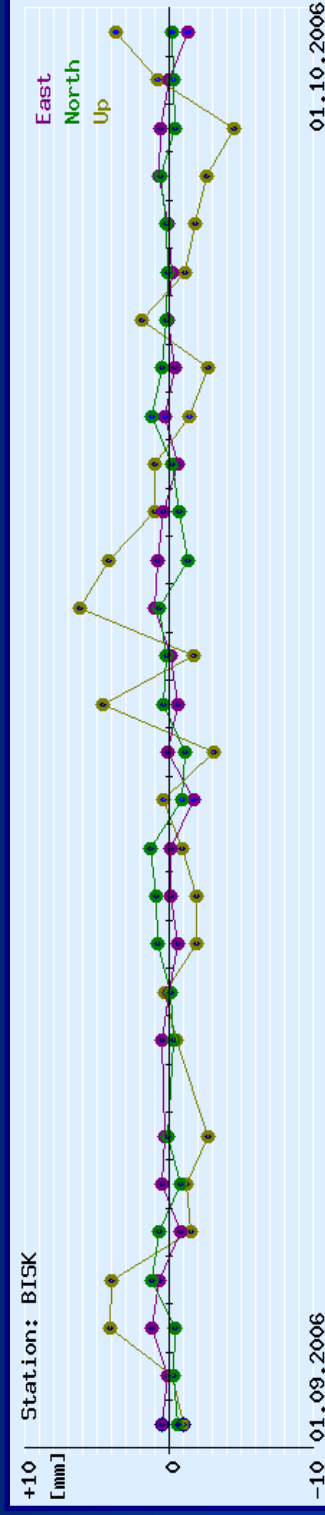
Solution accuracy – vertical component



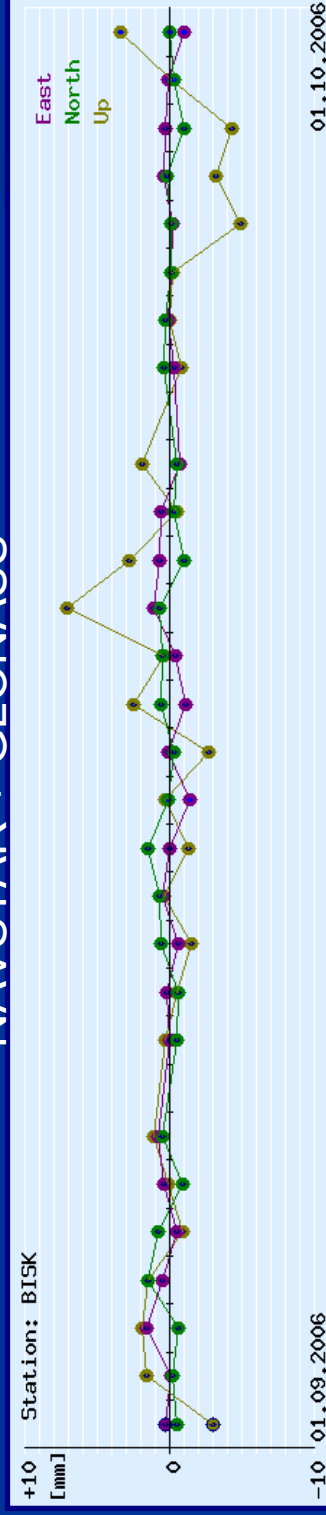
- the combined solution shows lower RMS for most days

Time series comparison

NAVSTAR



NAVSTAR + GLONASS



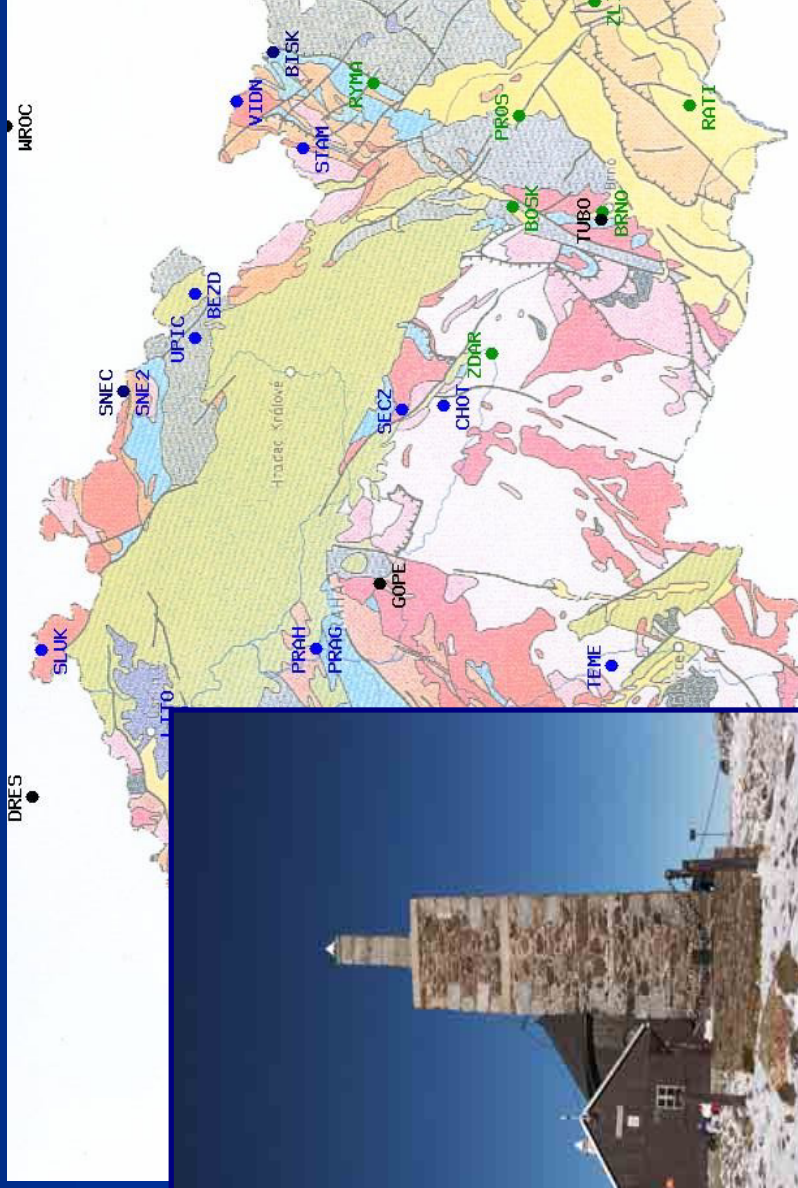
- the difference in the vertical component is caused by wake determination of the troposphere parameters

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GEONAS mountain observatories

BISK

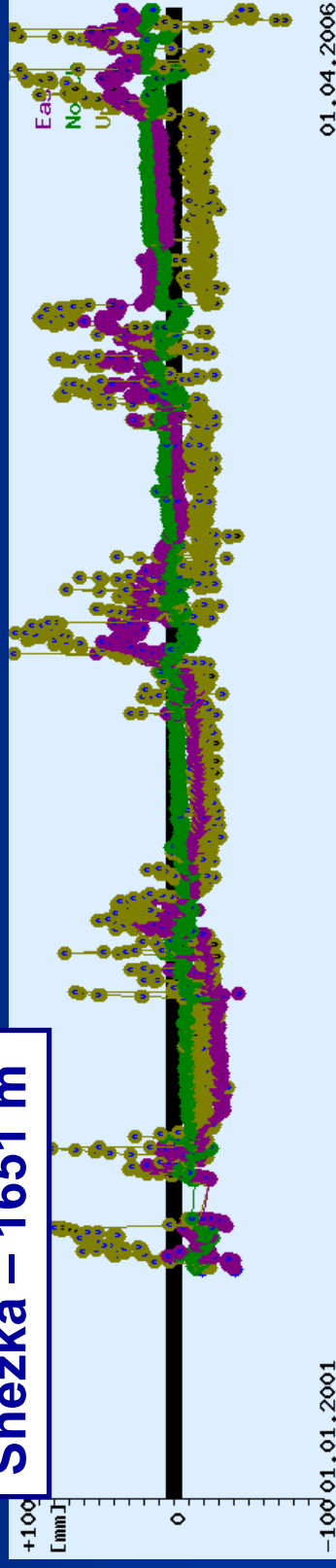


SNEC

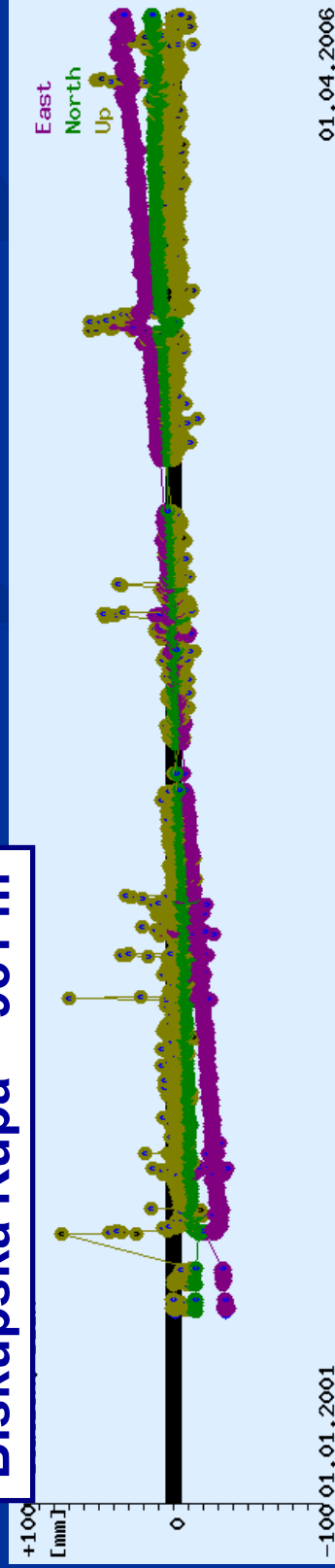


Time series analysis

Sněžka – 1651 m



Biskupská Kupa – 951 m



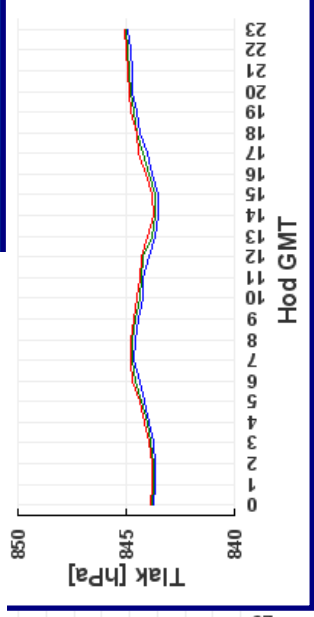
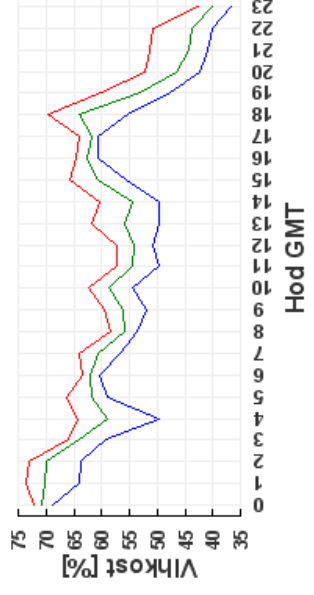
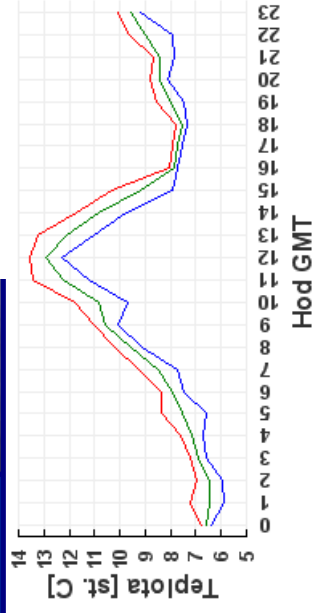
Meteorological data registration

Sněžka – 16.3.2006

Web camera for monitoring of the snow coverage



Meteorological sensors – temperature, humidity, pressure



Antenna snow cover visual evaluation



Classification of the snow cover

0 – no snow cover

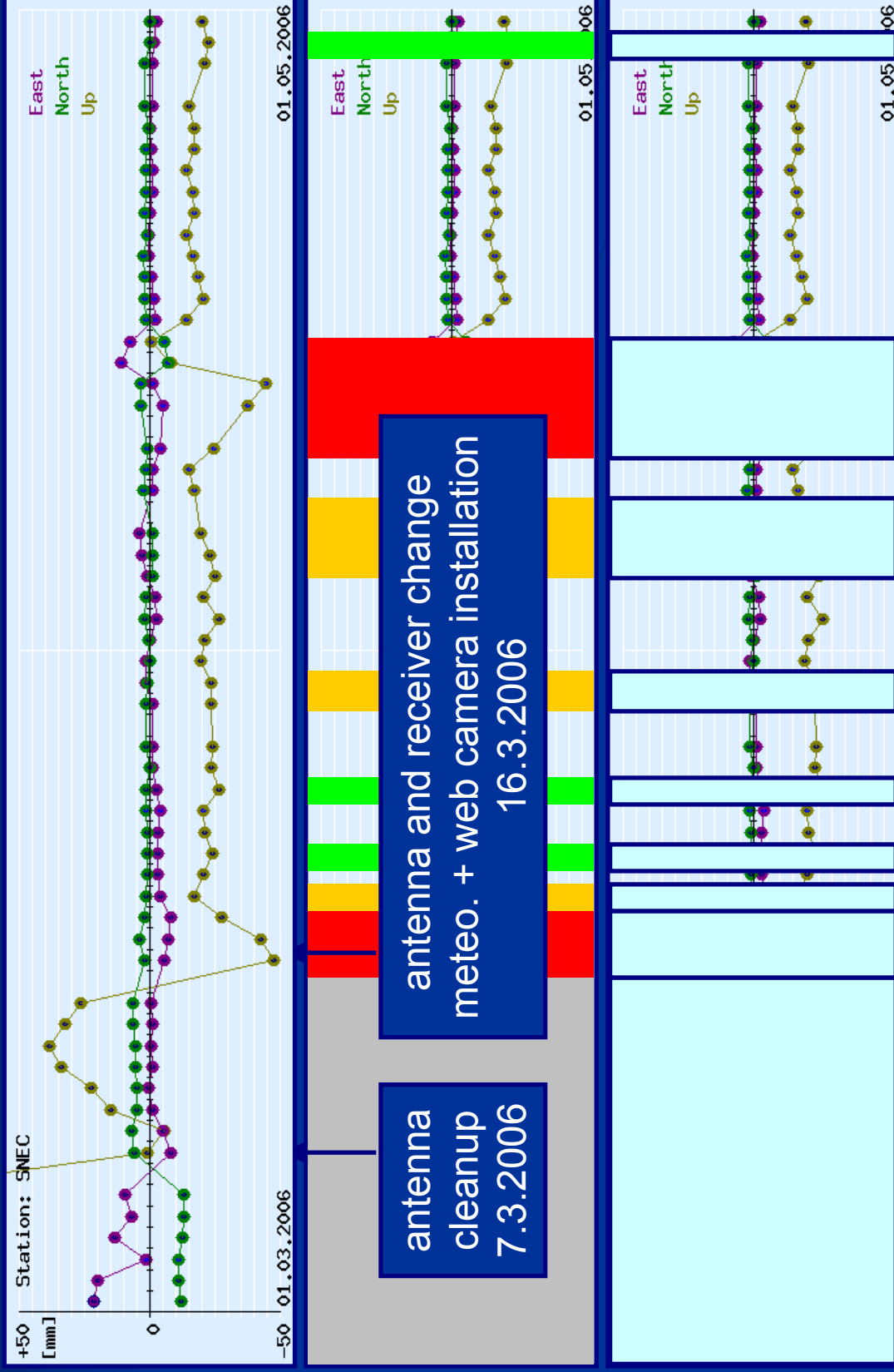
1 – cannot be identified or possible slight cover

2 – low snow cover

3 – thick or asym. snow cover

4 – cannot be identified (usually 1-2 according to temp. and situation of the surrounding days)

Correlation of the snow covered antenna with position anomaly



Conclusions

- time series of the GNSS antennas show better stability with the use of the both satellite systems
- GLONASS signals processing approx. doubles the number of determined parameters
- the observed GPS antenna position anomalies in winter correlate with snow cover of the antenna
- after the removal of the periods with the snow covered antenna time series indicated better repeatability

The end



Thank you for your attention